



Calibrated during C.P



Geometric current analysis:

Pixel Location Accuracy:

Monitoring

- SSC product based –

Geometric calibration update.

Pixel Geolocation Accuracy. First Characterization.

- Geocoded products based -



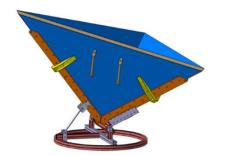
Test Data Set:

Almost 150 DTs over INTA Corner Reflectors:

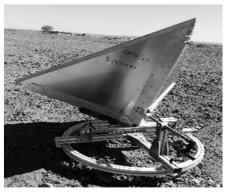
Right Looking acquisitions Variability:

Incidence Angles
Asc / Des Geometry
Imaging Mode
Polarization









On Ground Equipment

29 Corner Reflectors 1.0m & 1.5m size

Pixel Location Accuracy

Monitoring method

Azimuth Shift Internal Delay

- SSC product based -

Total Datatakes: 146

Measurements: 506

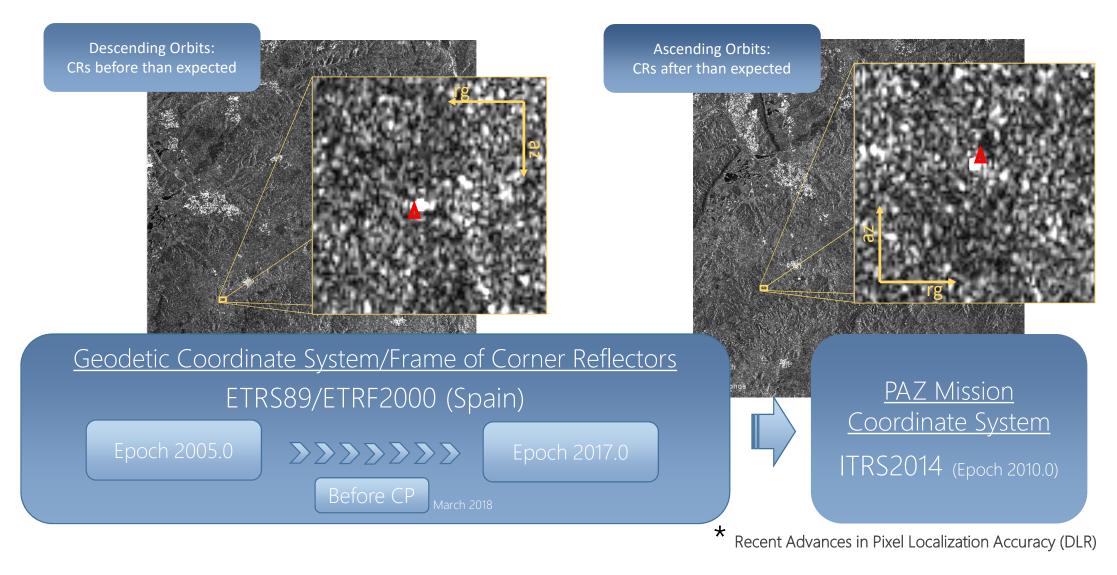
Geometric Calibration Update



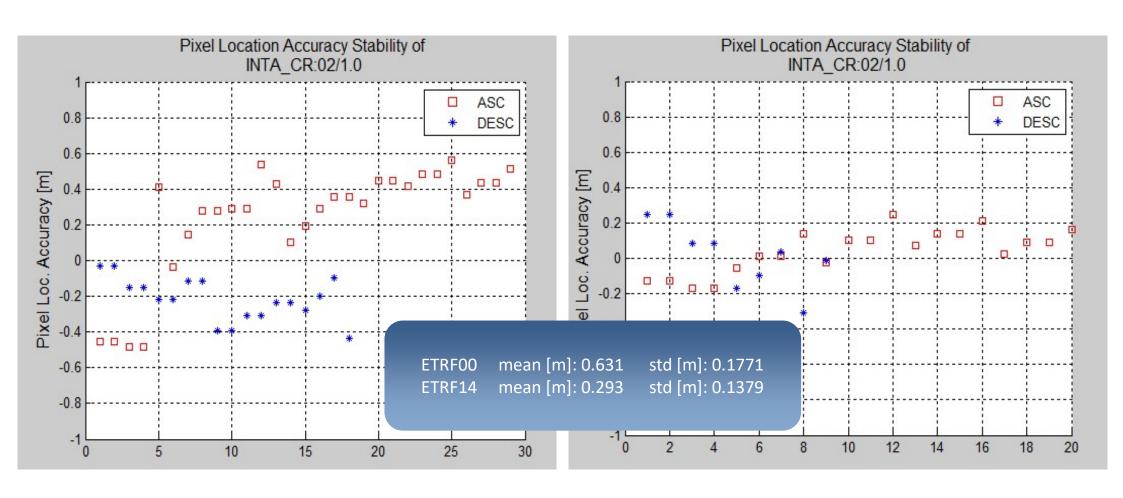
Results of polarization verification

Polarization Mode	Range Mean [m]	Azimuth Mean [m]	Pixel Location Accurazy Mean [m]	Pixel Location Accurazy STD [m]
S (HH)	0.151	0.163	0.245	0.132
S (VV)	0.169	0.165	0.263	0.160
D (HH)	0.099	0.250	0.273	0.143
D (VV)	0.076	0.228	0.287	0.140

Radar Coordinates Offset identified. Coordinate Systems Misinterpretation *



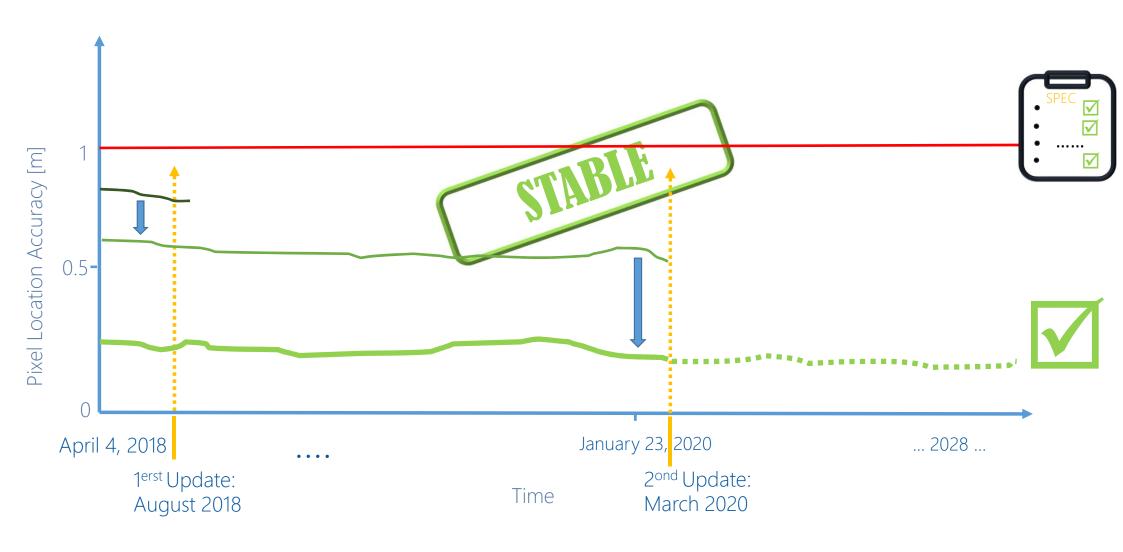
Results of Coordinate System Correction: Pixel Location Accuracy



Results of Orbit direction Analysis

Orbit Direction	Range Mean [m]	Azimuth Mean [m]	Pixel Location Accurazy Mean [m]	Pixel Location Accurazy STD [m]
ASC	0.187	0.134	0.247	0.143
DESC	0.197	0.126	0.257	0.140

Conclusion of Geometric Analysis



Pixel Geolocation Accuracy

First characterization

Easting UTC Northing UTC

- Geocoded product based -

GEC_SE & GEC_RE
EEC_SE & EEC_RE

Measurements: 1500

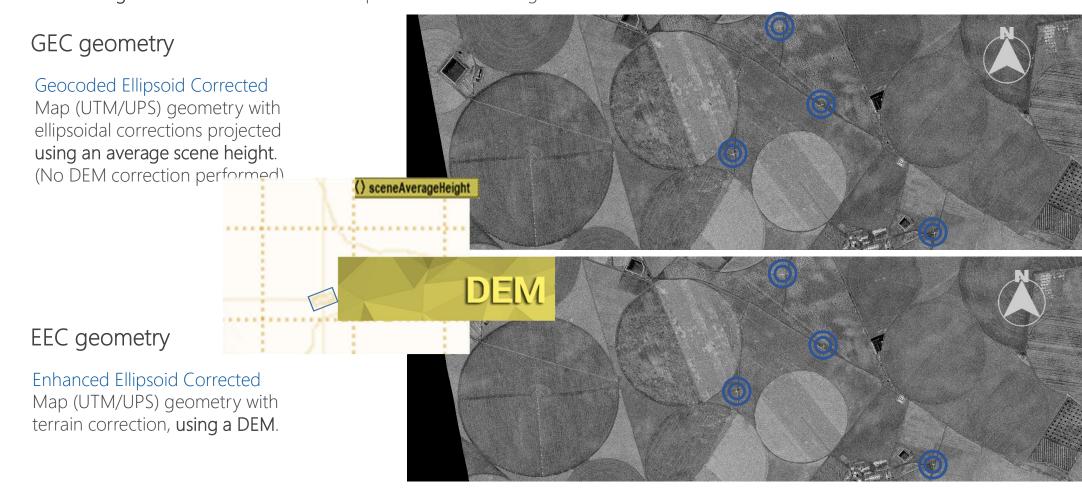


PAZ geocoded products:

Once solved Geometric Calibration. Main error sources of pixel location accuracy in geocoded products are:

Atmospheric Path Delay: PAZ products contain annotation of signal propagation delay, correction implemented in PAZ processor. Orbit Accuracy: PAZ Rapid Orbit (2m) – PAZ Science Orbit (0,20m)

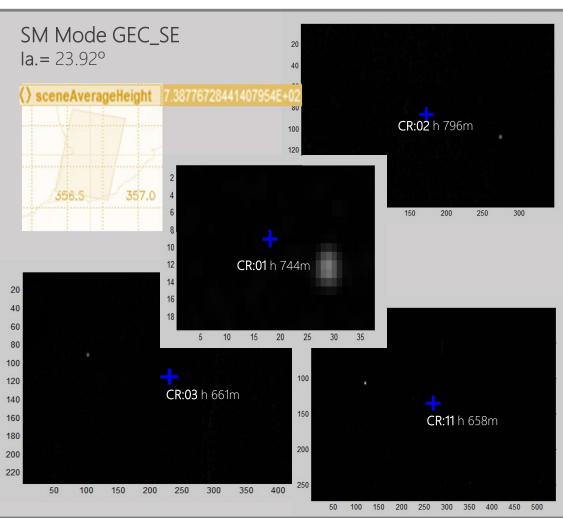
Terrain height error combined wiht the acquisition incidence angle.



GEC products location assessment:

Errors locally variables. As expected due to height difference. Easting direction especially sensible to height difference: mostly rg direction.

	Height	Max. Location	GEC-SE		
	difference w.r.t. mean scene (m)	error due to height difference (m)	RMS Easting (m)	RMS Northing (m)	
SM-Mod	SM-Mode Strip_004 (Incidence angle = 23.92°)				
CR:01	5.97	13.442	13.25	4.11	
CR:02	57.54	129.46	127.00	26.18	
CR:03	76.82	172.85	159.32	29.87	
CR:11	90.10	202.73	188.03	35.76	
SL-Mode	Sp	ot_090 (Incidence	angle = 52.25°)		
CR:03	40.26	31.00	30.02	3.43	
CR:11	53.56	41.24	41.64	5.23	
CR:22	43.56	33.54	32.49	4.04	
HS-Mode	HS-Mode Spot_063 (Incidence angle = 44.03°))	
CR:07	10.23	10.54	10.53	0.45	
CR:15	6.68	6.89	7.34	0.08	
CR:16	4.48	4.61	5.05	0.23	



EEC products location assessment:

Errors as expected due PAZ Digital Elevation Model. Easting direction especially sensible to height difference: mostly rg direction. Differences between RE and SE product variants are related to pixel size.

	EEC-RE		EEC-SE		
	RMS Easting (m)	RMS Northing (m)	RMS Easting (m)	RMS Northing (m)	
SM-Mode					
strip_004	6.92	5.81	2.37	1.99	
strip_008	6.00	3.57	2.40	1.42	
strip_013	4.96	3.08	2.20	1.70	
SL-Mode					
spot_018	4.63	1.82	1.81	0.44	
spot_090	2.75	1.62	0.33	0.55	
HS-Mode					
spot_016	3.45	3.26	3.01	1.36	
spot_063	2.85	1.01	2.85	0.62	
spot_100	2.30	0.94	0.46	0.18	

	Incidence Angle (°)	Displacement Factor	Max. Abs. Location Error (m)
strip_004	23.92	2.25	36.08
strip_008	33.16	1.53	24.49
strip_013	42.75	1.08	17.31
	24.86	2.16	34.52
spot_063	44.03	1.03	16.55
spot_090	52.25	0.77	12.39
spot_100	54.81	0.71	11.28

SRTM/ C Band DEM based.



